Flight Simulation

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The project

Components

- 3D physics simulation
- 3D graphics
- 3D terrain (landscape)
- Collision detection

Language & libraries

- C++
- SFML
- OpenGL
- GLM

Purpose

• For the sake of learning

3D Graphics



Physics from 2D to 3D, Airfoil Segmentation

Root and tip sections have different velocities when the plane rotates.



Physics from 2D to 3D, Inertia Matrix

- In 2D inertia is a scalar.
- In 3D inertia is a 3x3 matrix.

$$\mathbf{I} = \begin{bmatrix} I_{11} & I_{12} & I_{13} \\ I_{21} & I_{22} & I_{23} \\ I_{31} & I_{32} & I_{33} \end{bmatrix} = \begin{bmatrix} I_{xx} & I_{xy} & I_{xz} \\ I_{yx} & I_{yy} & I_{yz} \\ I_{zx} & I_{zy} & I_{zz} \end{bmatrix}.$$
^[1]

Physics from 2D to 3D, Inertia Matrix



$$I_{11} = I_{xx} = \sum_{k=1}^{N} m_k \left(y_k^2 + z_k^2 \right),$$

$$I_{22} = I_{yy} = \sum_{k=1}^{N} m_k \left(x_k^2 + z_k^2 \right),$$

$$I_{33} = I_{zz} = \sum_{k=1}^{N} m_k \left(x_k^2 + y_k^2 \right),$$

$$I_{12} = I_{21} = I_{xy} = -\sum_{k=1}^{N} m_k x_k y_k,$$

$$I_{13} = I_{31} = I_{xz} = -\sum_{k=1}^{N} m_k x_k z_k,$$

$$I_{23} = I_{32} = I_{yz} = -\sum_{k=1}^{N} m_k y_k z_k.$$
[1]

Wheels in 3D



No contact no force from the wheels

(View from side)



- Δy how much the spring is compressed
- F all other forces pushing on wheel
- N normal force
- S spring force
- R rolling friction force

(View from side)

Wheels in 3D



Cf - friction coefficient when wheel moves forward/backward Cz - friction coefficient when wheel moves sideways V - velocity In this case coefficient will be closer to Cf

(View from top)

3D Graphics

- Terrain is rendered using heightmap
- Different levels of detail based on distance
- Terrain is textured using splatmap
- Deferred rendering
- 3D objects are loaded from AC3D file format



- Problem
 - Is a leaf node's neighboring node smaller?
- Assumption
 - Neighbor is either 2 times smaller, 2 times bigger, or of the same size.

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- Victorbush's solution [2]
 - Take a pos at the edge of a node
 - $\circ \quad \text{Add some } \epsilon$
 - DFS for a node that contains the position



- Our solution
 - Do a breadth first traversal from largest node down to leaf nodes.
 - Set neighbors of children along the way.



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 - Larger leaf nodes don't know smaller neighbors.
 - Smaller neighbors know larger neighbors.



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- Victorbush's solution [2]
 DFS for every leaf node
- Our solution
 - 1 breadth first traversal

References

- 1) Moment of inertia wiki page: <u>https://en.wikipedia.org/wiki/Moment_of_inertia</u>
- 2) Victorbush, Tessellated Terrain Rendering with Dynamic LOD: https://victorbush.com/2015/01/tessellated-terrain/



- Alen German - Auyez Zhumashev

Computer Science Department

Clouds



- Transmittance the ratio of light that reaches the eye.
- Light_eye = T(extinction_coeff, distance)
- Transmittance is given by Lambert-Beer law
- $T(\sigma, d) = exp(-\sigma * d)$





