

Flight Simulation

Advisor:

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Team:

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The project

Components

- 3D physics simulation
- 3D graphics
- 3D terrain (landscape)
- Collision detection

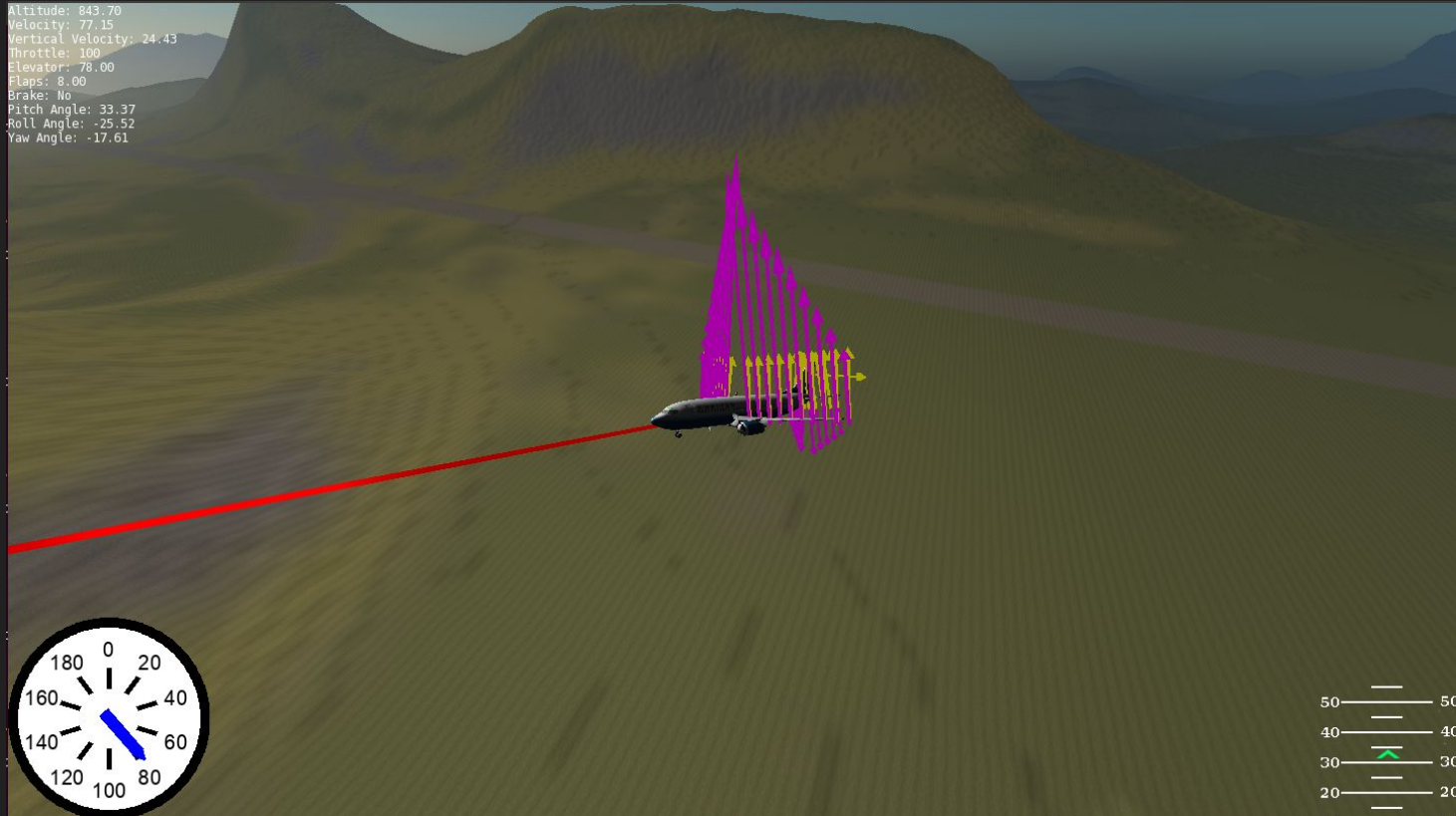
Language & libraries

- C++
- SFML
- OpenGL
- GLM

Purpose

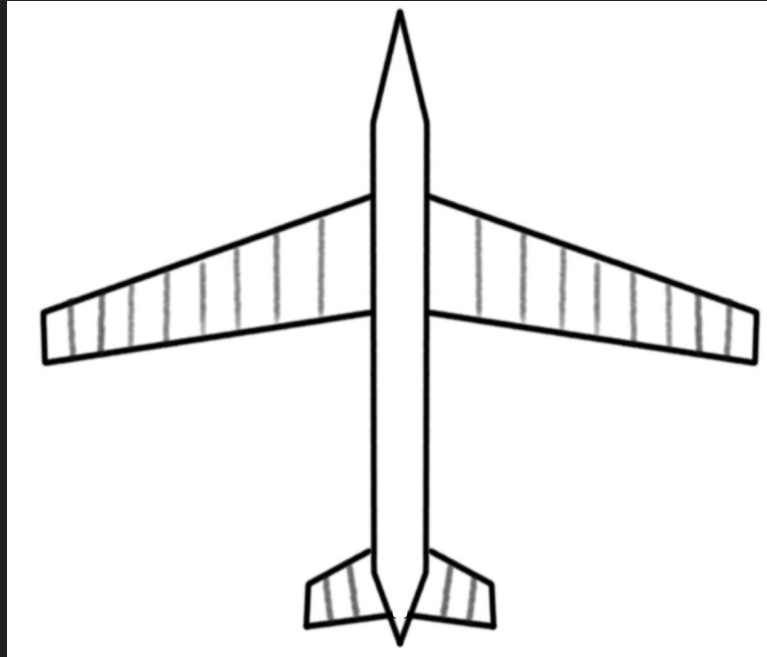
- For the sake of learning

3D Graphics



Physics from 2D to 3D, Airfoil Segmentation

- Root and tip sections have different velocities when the plane rotates.

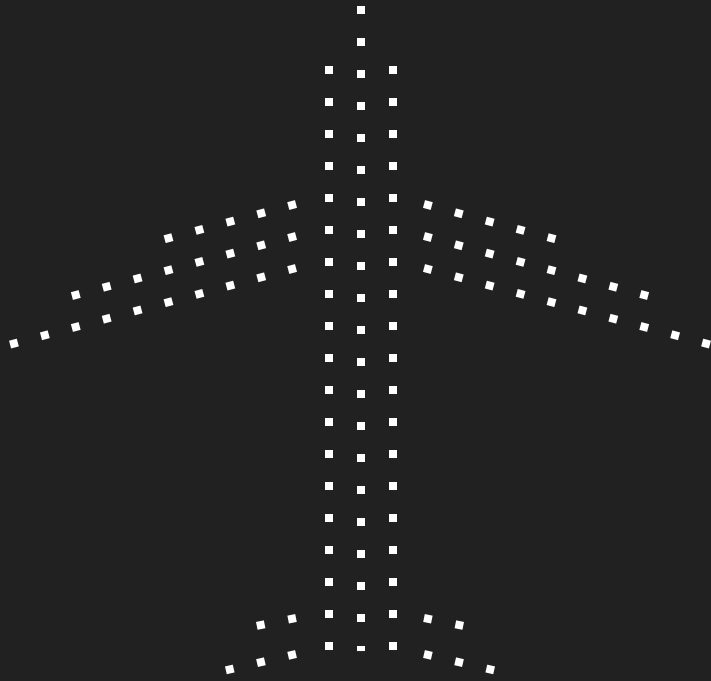


Physics from 2D to 3D, Inertia Matrix

- In 2D inertia is a scalar.
- In 3D inertia is a 3x3 matrix.

$$\mathbf{I} = \begin{bmatrix} I_{11} & I_{12} & I_{13} \\ I_{21} & I_{22} & I_{23} \\ I_{31} & I_{32} & I_{33} \end{bmatrix} = \begin{bmatrix} I_{xx} & I_{xy} & I_{xz} \\ I_{yx} & I_{yy} & I_{yz} \\ I_{zx} & I_{zy} & I_{zz} \end{bmatrix}. \quad [1]$$

Physics from 2D to 3D, Inertia Matrix



$$I_{11} = I_{xx} = \sum_{k=1}^N m_k (y_k^2 + z_k^2),$$

$$I_{22} = I_{yy} = \sum_{k=1}^N m_k (x_k^2 + z_k^2),$$

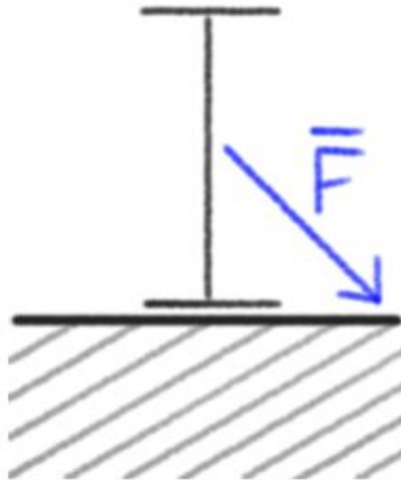
$$I_{33} = I_{zz} = \sum_{k=1}^N m_k (x_k^2 + y_k^2),$$

$$I_{12} = I_{21} = I_{xy} = - \sum_{k=1}^N m_k x_k y_k,$$

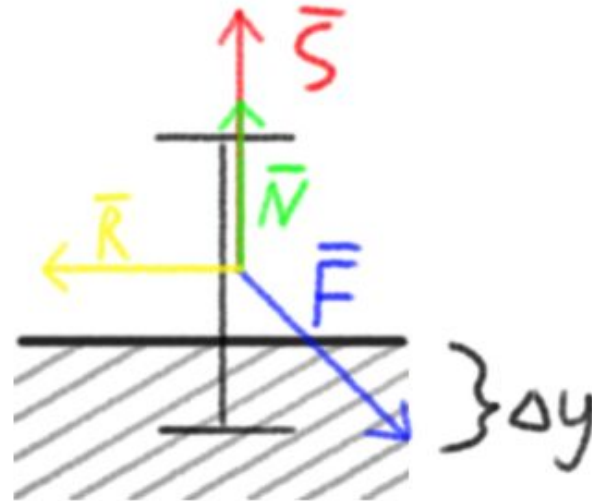
$$I_{13} = I_{31} = I_{xz} = - \sum_{k=1}^N m_k x_k z_k,$$

$$I_{23} = I_{32} = I_{yz} = - \sum_{k=1}^N m_k y_k z_k. \quad [1]$$

Wheels in 3D



No contact -
no force from the wheels
(View from side)



Δy - how much the spring is compressed
 \vec{F} - all other forces pushing on wheel
 \vec{N} - normal force
 \vec{S} - spring force
 \vec{R} - rolling friction force

(View from side)

Wheels in 3D



C_f - friction coefficient when wheel moves forward/backward

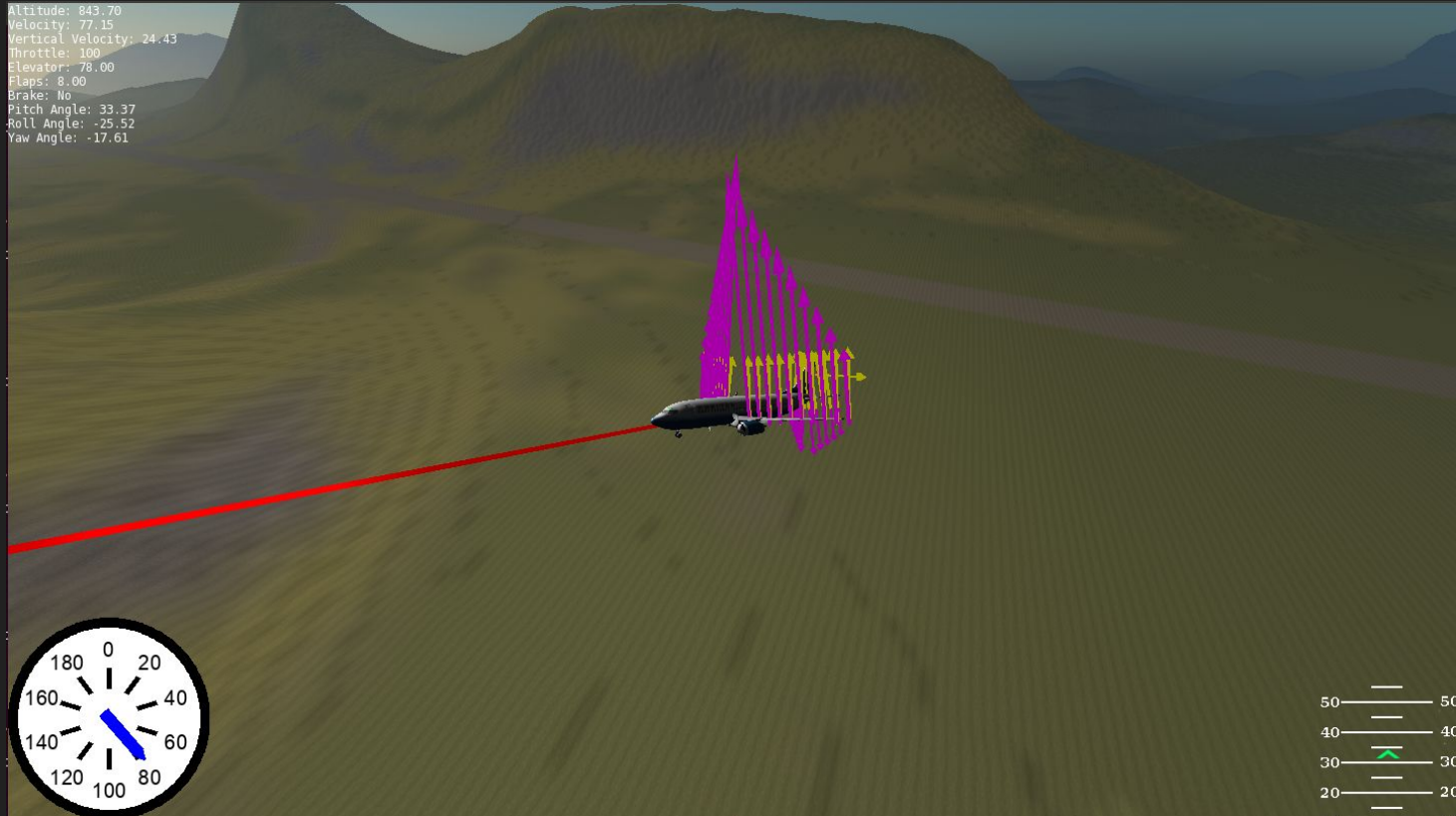
C_s - friction coefficient when wheel moves sideways

V - velocity

In this case coefficient will be closer to C_f

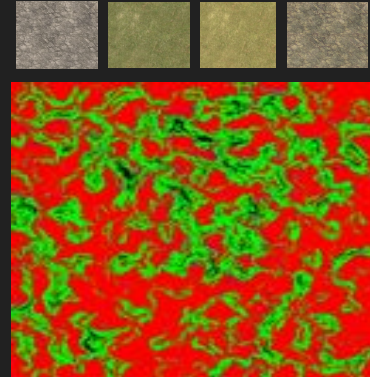
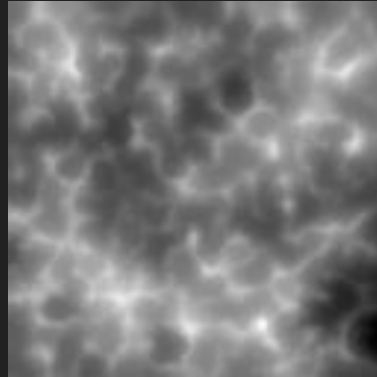
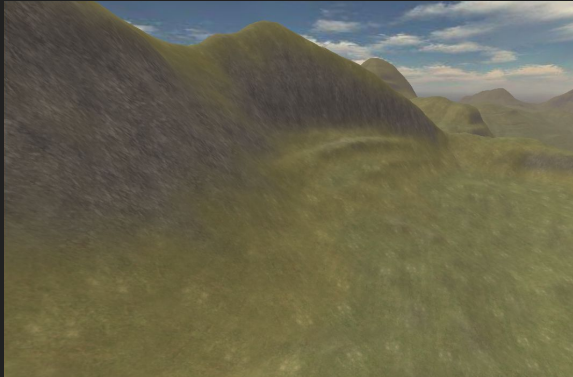
(View from top)

3D Graphics



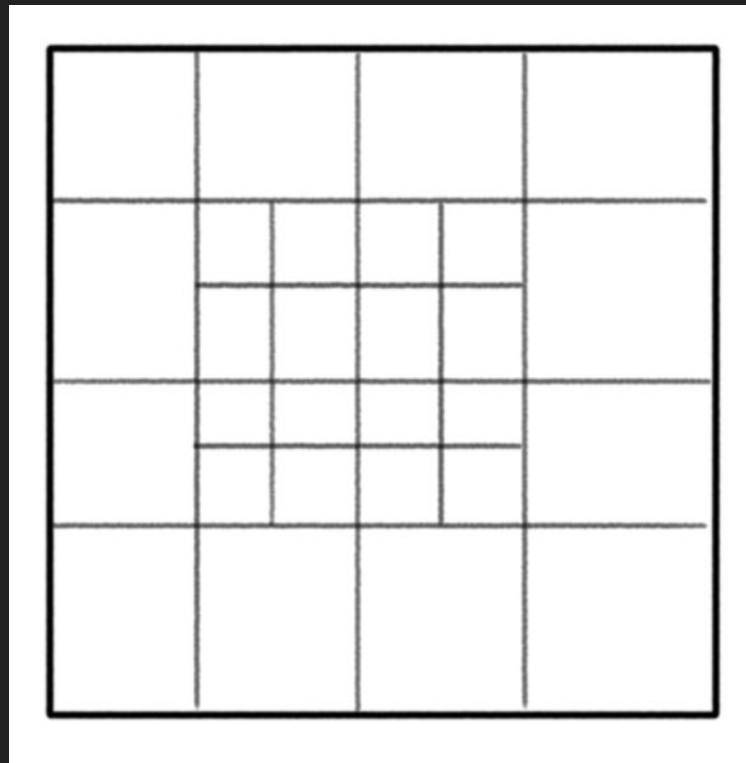
3D Graphics

- Terrain is rendered using heightmap
- Different levels of detail based on distance
- Terrain is textured using splatmap
- Deferred rendering
- 3D objects are loaded from AC3D file format



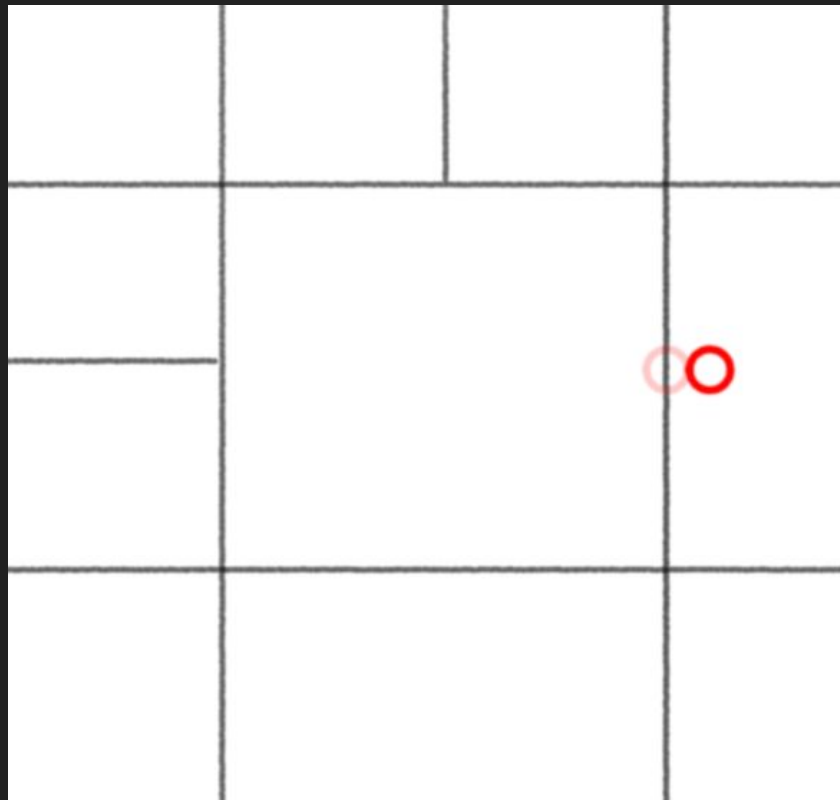
Quadtree neighbor retrieval

- Problem
 - Is a leaf node's neighboring node smaller?
- Assumption
 - Neighbor is either 2 times smaller, 2 times bigger, or of the same size.



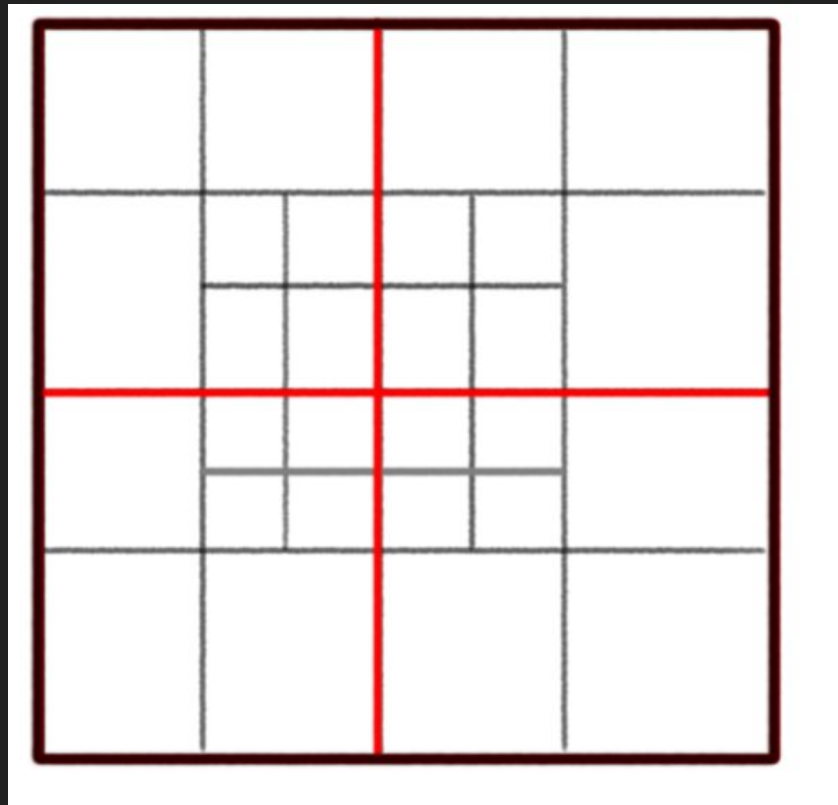
Quadtree neighbor retrieval

- Victorbush's solution [2]
 - Take a pos at the edge of a node
 - Add some ϵ
 - DFS for a node that contains the position



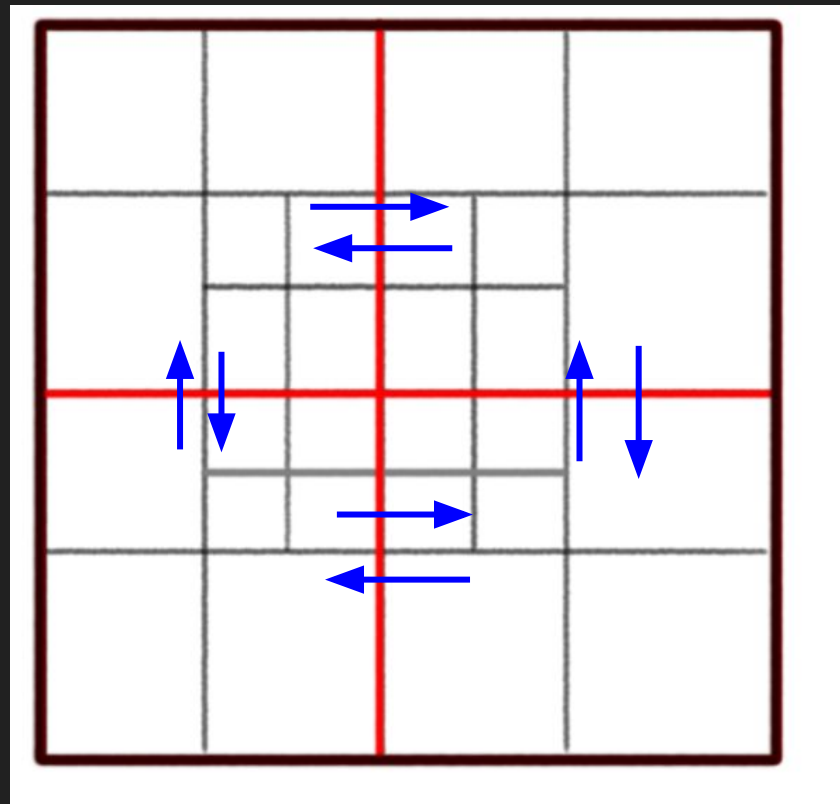
Quadtree neighbor retrieval

- Our solution
 - Do a breadth first traversal from largest node down to leaf nodes.
 - Set neighbors of children along the way.



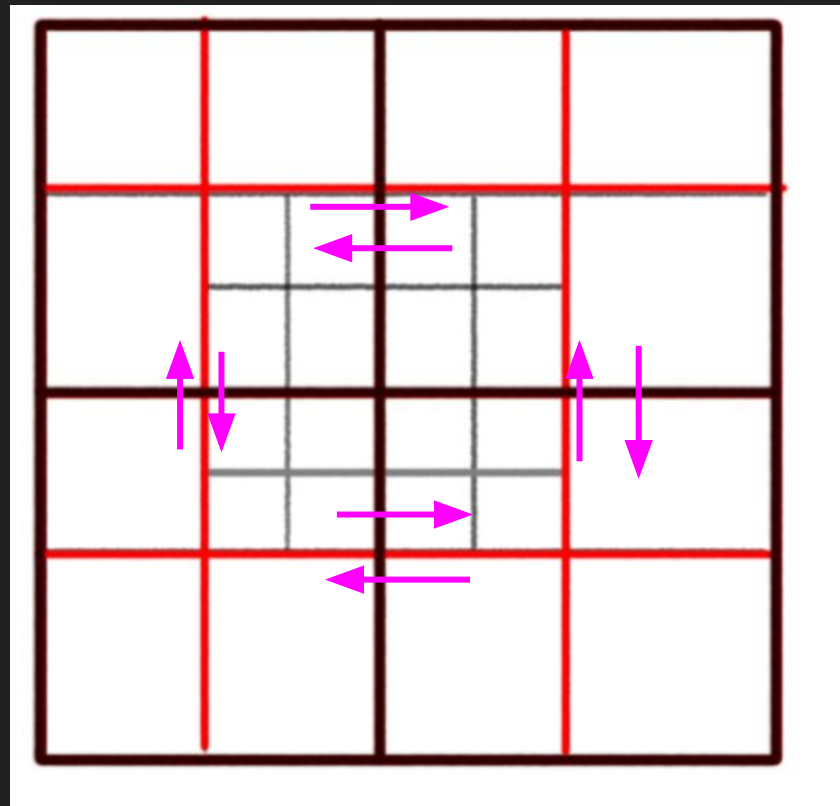
Quadtree neighbor retrieval

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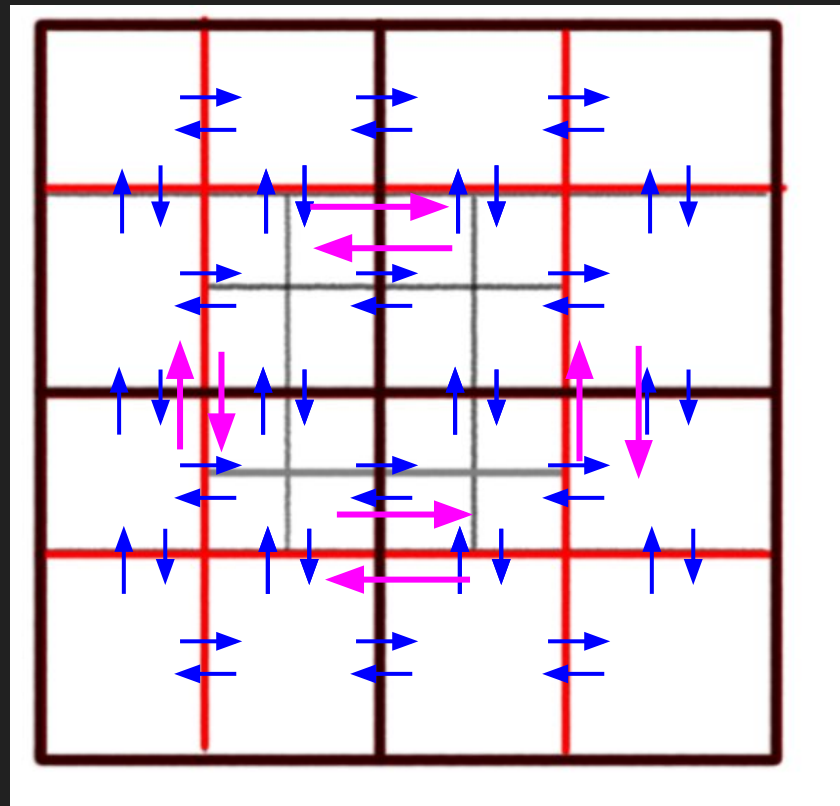
Quadtree neighbor retrieval

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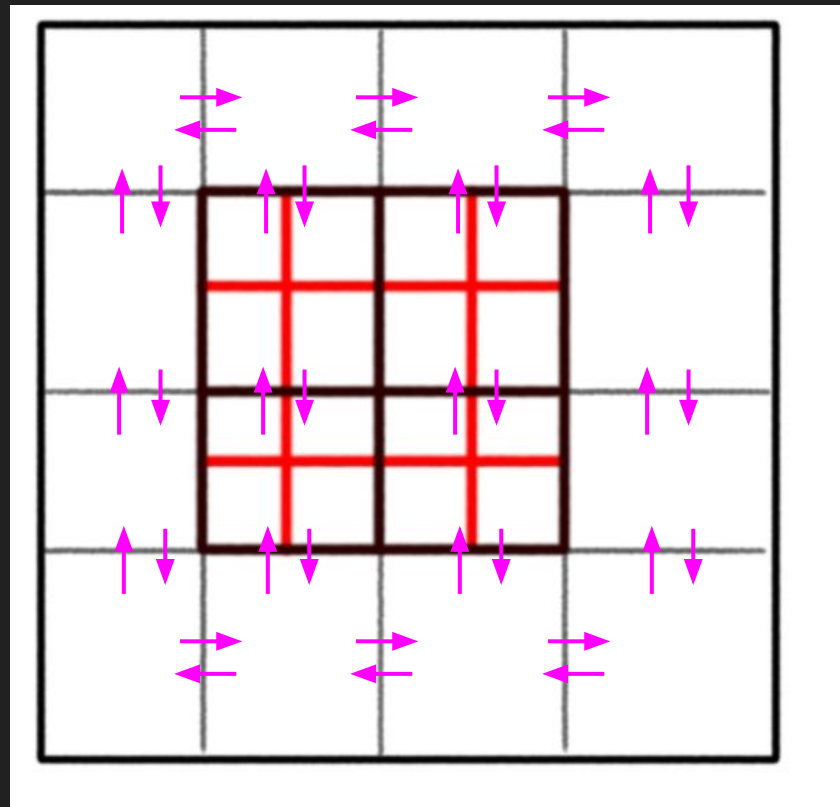
Quadtree neighbor retrieval

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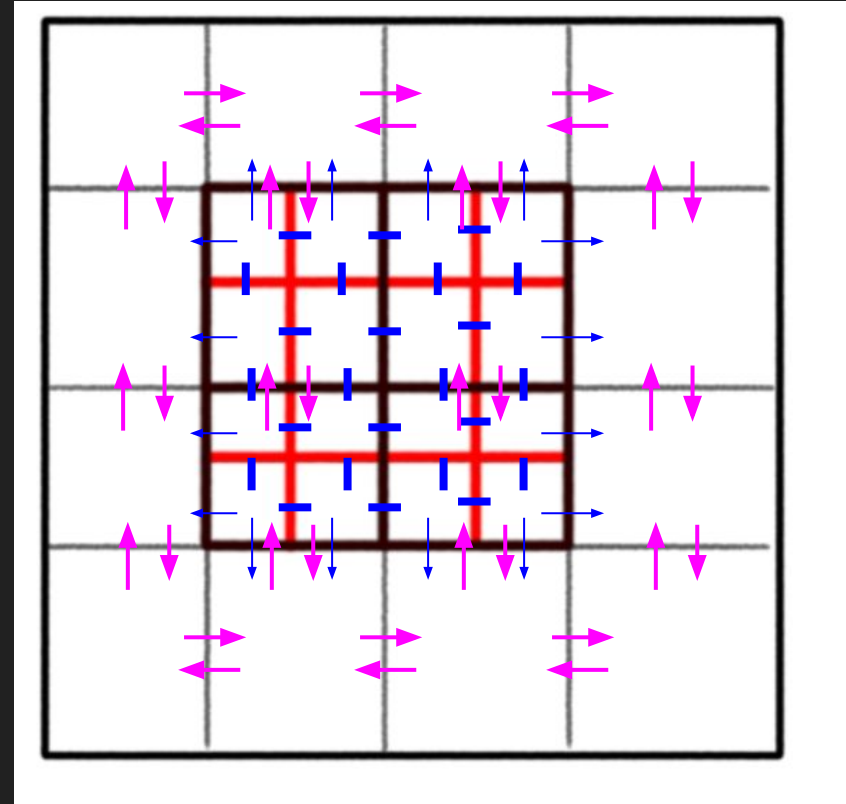
Quadtree neighbor retrieval

- Our solution
 - Do a breadth first traversal from largest node down to leaf nodes.
 - Set neighbors of children along the way.
 - Larger leaf nodes don't know smaller neighbors.
 - Smaller neighbors know larger neighbors.



Quadtree neighbor retrieval

- Our solution
 - Do a breadth first traversal from largest node down to leaf nodes.
 - Set neighbors of children along the way.
 - Larger leaf nodes don't know smaller neighbors.
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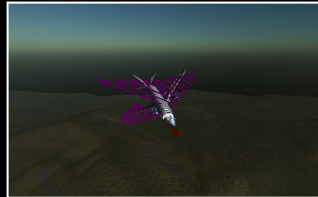
Quadtree neighbor retrieval

- Victorbush's solution [2]
 - DFS for every leaf node
- Our solution
 - 1 breadth first traversal

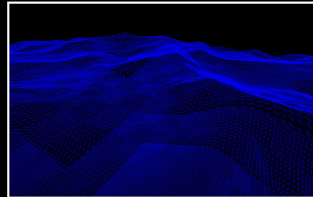
References

- 1) Moment of inertia wiki page:
https://en.wikipedia.org/wiki/Moment_of_inertia
- 2) Victorbush, Tessellated Terrain Rendering with Dynamic LOD:
<https://victorbush.com/2015/01/tessellated-terrain/>

FLIGHT SIMULATOR



Realistic physics
Atmospheric scattering



Massive terrain with
dynamic level of detail

We wanted to learn about low-level graphics programming and 3D physics simulation. This project is a byproduct of our learning experience. It was done using C++ and OpenGL.

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- Alisher Shakhiev
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- Auyez Zhumashev

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- Hans De Nivelte

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Clouds

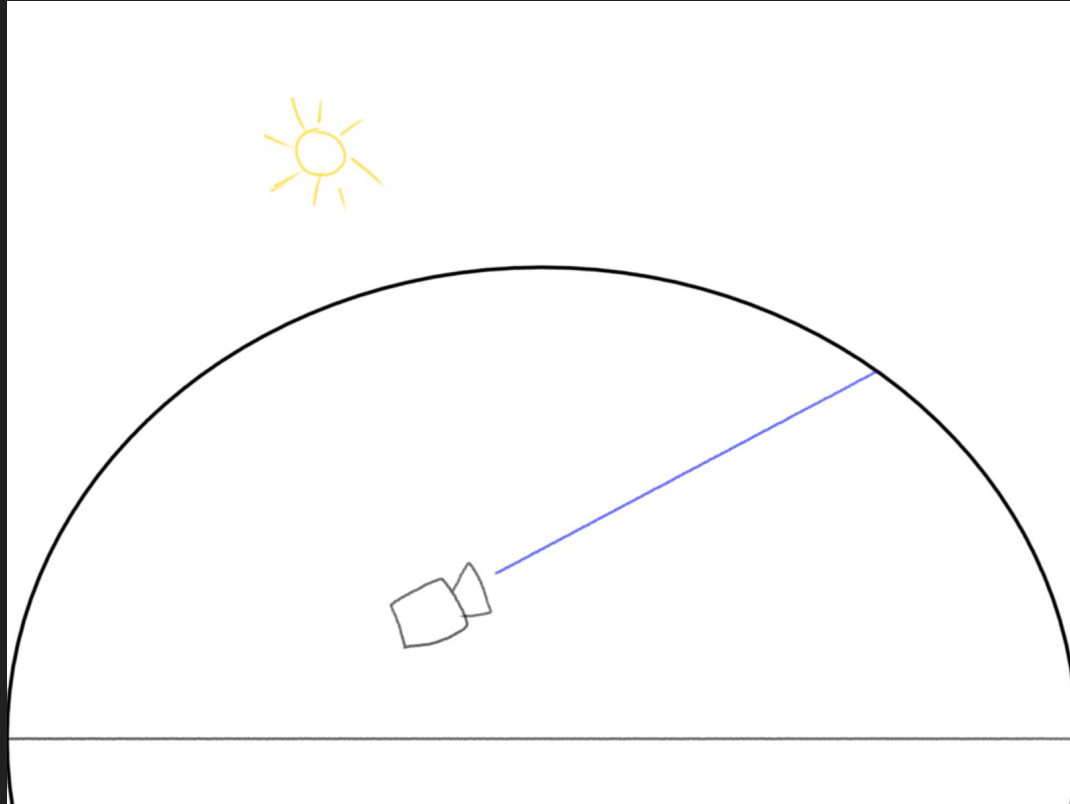


Atmospheric Scattering

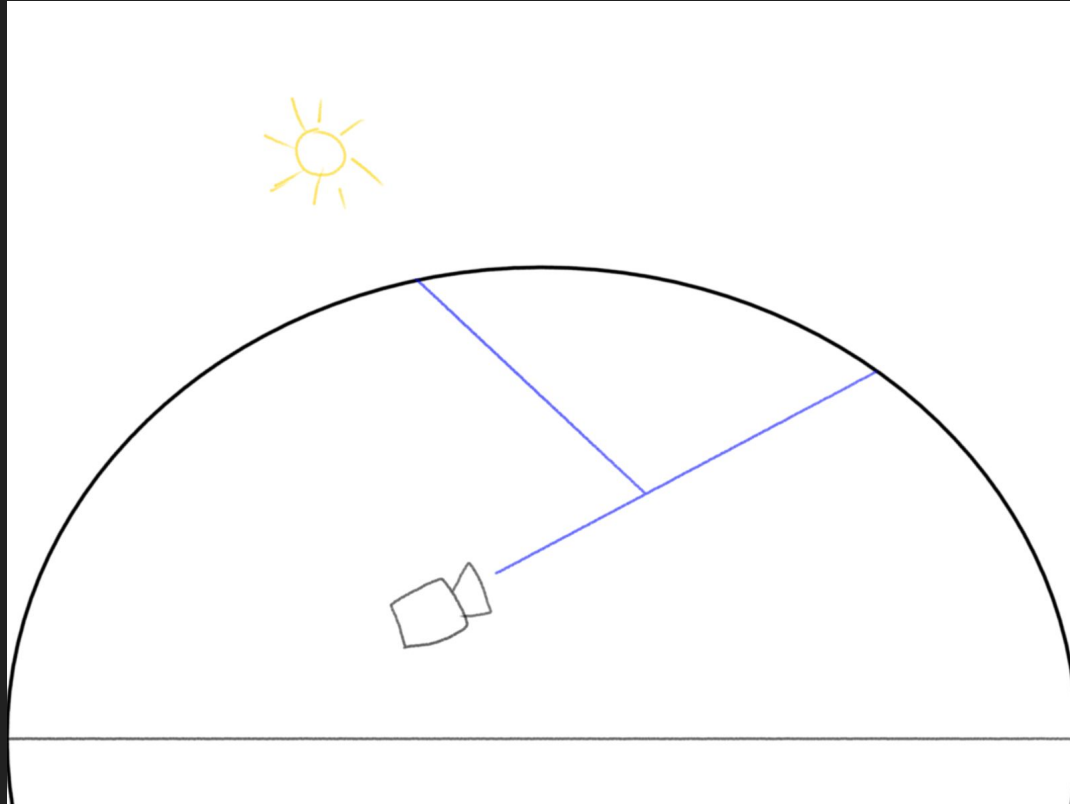
- Transmittance - the ratio of light that reaches the eye.
- **Light_eye = T(extinction_coeff, distance)**

- Transmittance is given by Lambert-Beer law
- **$T(\sigma, d) = \exp(-\sigma * d)$**

Atmospheric Scattering



Atmospheric Scattering



Atmospheric Scattering

